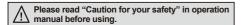
# Small and light, common type

### Features

- Easy to mount at a narrow space with small size and light weight.
- Convenient to adjust the sensitivity by external sensitivity adjustment control. (Diffuse reflective type only)
- Easy to mount by screw type in mounting hole.
- Reverse power polarity protection circuit.







# Specifications

Model		BM3M-TDT	BM1M-MDT	BM200-DDT	
Sensing type		Through-beam	Retroreflective	Diffuse reflective	
Sensing distance		3m	0.1 to 1m <sup>*1</sup>	200mm <sup>ж2</sup>	
Sensing target		Opaque materials of Min. ø8mm	Opaque materials of Min. ø60mm	Translucent, Opaque materials	
Hysteresis		M		Max. 10% at rated settingdistance	
Response time		Max. 3ms			
Power supply		12-24VDC ±10%(Ripple P-P : Max. 10%)			
Current consumption		Max. 45mA	Max. 40mA		
Light source		Infrared LED(940nm)			
Sensitivity adjustment		Fixed		Adjustable VR	
Operation mode		Dark ON		Light ON(Dark ON: Option)	
Control output		NPN open collector output  ◆Load voltage : Max. 30VDC ◆Load current : Max. 100mA ◆Residual voltage : Max. 1V			
Protection circuit		Reverse polarity protection			
Indication		Operation indicator : red LED			
Insulation resistance		Min. 20MΩ(at 500VDC megger)			
Noise resistance		±240V the square wave noise(pulse width : 1μs) by the noise simulator			
Dielectric strength		1,000VAC 50/60Hz for 1minute			
Vibration		1.5mm amplitude or 300m/s² at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours			
Shock		500m/s²(approx. 50G) in each of X, Y, Z directions for 3 times			
	Ambient illumination	Sunlight: Max. 11,0001x Incandescent lamp: Max. 3,0001x (Receiver illumination)			
Environ- ment	Ambient temperature	-10 to 60°C, storage : -25 to 70°C			
	Ambient humidity	35 to 85%RH, storage : 35 to 85%RH			
Material		Case : ABS, Sensing part : PC	Case : ABS, Sensing part : Acrylic(Retroreflective: PC)		
Cable		ø4, 3-wire, Length : 2m(Emitter of through-beam type: ø4, 2-wire, Length : 2m) (AWG22, Core diameter : 0.08mm, Numner of cores : 60, Insulator out diameter : ø1.25)			
Acce-	Individual	_	Reflector(MS-2)	VR adjustment driver	
ssories	Common	Mounting bracket, Bolts/nuts			
Approval		CE			
Unit weight		Approx. 170g	Approx. 105g	Approx. 88g	

X1: It is mounting distance between sensor and reflector MS-2 and it is same when MS-5 is used. It is detectable under 0.1m.

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X2: It is for Non-glossy white paper(200×200mm)

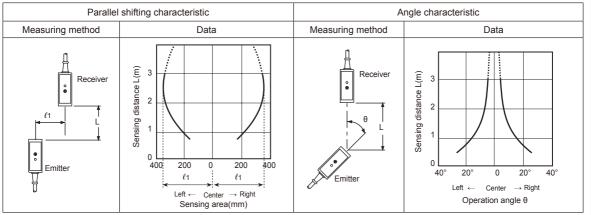
XThe temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

# **Amplifier Built-in type for General Purpose**

### **■** Feature data

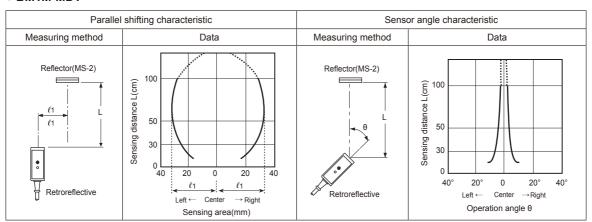
### Through-beam type

#### • BM3M-TDT



# © Retroreflective type

#### BM1M-MDT



### Retroreflective type

#### BM1M-MDT

Reflector angle characteristic						
Measuring method	Data					
Reflector(MS-2)	$(a) \begin{picture}(20,0) \put(0,0){\line(1,0){100}} \put(0,0){\line(1,0)$					

## O Diffuse reflective type

### • BM200-DDT

Sensi	Sensing area characteristic					
Measuring method	Data					
Standard sensing target: Non-glossy white paper 200×200mm	(Eb) 1 20 30 20 0 20 30 20 10 20 30 Left ← Center → Right Sensing area(mm)					

(C) Door/Area

(D) Proximity

(E) Pressure sensor

(I) SSR/

Power controller

(M) Tacho/ Speed/ Pulse meter

(P) Switching mode power supply

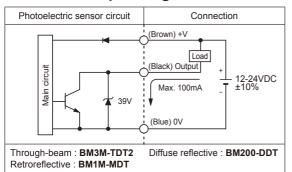
(Q) Stepper motor& Driver&Co

(R) Graphic/ Logic panel

(S) Field network device

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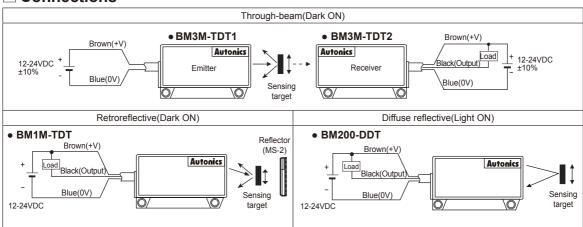
# **■** Control output diagram



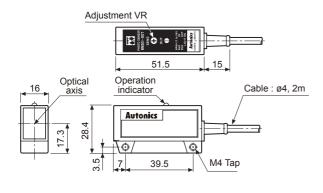
# Operation mode

Operation mode	Light ON			
Receiver operation	Received light			
Receiver operation	Interrupted light			
Operation indicator	ON			
(red LED)	OFF			
Transistor output	ON			
Transistor output	OFF			
Operation mode	Dark ON			
Possiver eneration	Received light			
Receiver operation	Interrupted light			
Operation indicator	ON			
(red LED)	OFF			
Transistor output	ON			
Transision output	OFF			

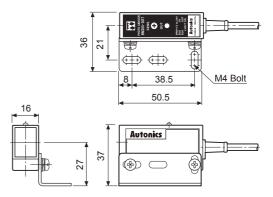
### Connections



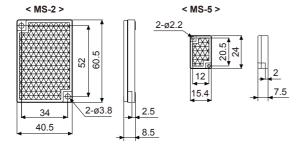
### Dimensions



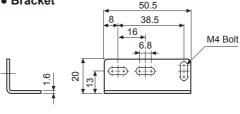
### Connect the bracket



#### Reflector



#### Bracket



(unit: mm)

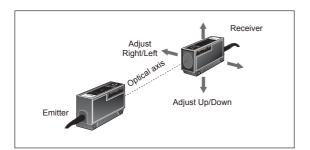
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# **Amplifier Built-in type for General Purpose**

## Mounting and sensitivity adjustment

### 

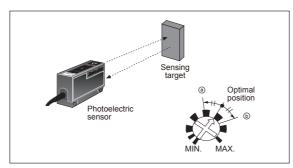
- Supply the power to the photoelectric sensor, after setting the emitter and the receiver facing each other.
- Set the receiver in center of position in the middle of the operation range of indicator adjusting the receiver or the emitter right and left, up and down.
- After adjustment, check the stability of operation putting the object at the optical axis.
- ※If the sensing target is translucent body or smaller than ø8mm, it can be missed by sensor cause light penetrate it.



### O Diffuse reflective type

- The sensitivity should be adjusted depending on a sensing target or mounting place.
- Set the target at a position to be detected by the beam, then turn the adjustment VR until position (a) where the operation indicator turns ON from min. position of the adjustment VR.
- Take the target out of the sensing area, then turn the adjustment VR until position 

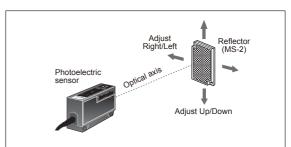
   where the the operation indicator turns ON. If the indicator dose not turn ON, max. position is
- Set the adjustment VR at the center of two switching position (a), (b).



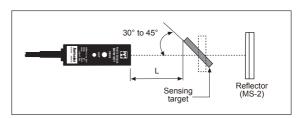
\*\*The sensing distance indicated on specification chart is for 200×200mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.

### Retroreflective type

- Supply the power to the photoelectric sensor, after setting the photoelectric sensor and the reflector(MS-2) in face to face.
- Set the photoelectric sensor in the position which indicator turns on, as adjusting the reflector or the sensor right and left, up and down.
- 3. Fix both units tightly after checking that the unit detects the target.
- XIf using more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.



※If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photoelectric sensor. Therefore put enough space between the target and the photoelectric sensor or the surface of the target should be installed at angle of 30° to 45° against optical axis.



XIf the mounting place is too narrow, please use MS-5 instead of MS-2.



(A) Photo electric sensor

(B) Fiber optic

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure

> F) lotary ncoder

(G) Connector/

(H) Temp.

(I) SSR/ Power controller

> (J) Counter

(IV)

-) anel

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching mode power supply

(Q) Stepper motor& Driver&Controlle

(R) Graphic/ Logic panel

(S) Field network device

> T) Software

U) Other

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